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Metric Learning: A Survey

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Abstract

The *metric learning* problem is concerned with learning a distance function tuned to a particular task, and has been shown to be useful when used in conjunction with nearest-neighbor methods and other techniques that rely on distances or similarities. This survey presents an overview of existing research in metric learning, including recent progress on scaling to high-dimensional feature spaces and to data sets with an extremely large number of data points. A goal of the survey is to present as unified as possible a framework under which existing research on metric learning can be cast. The first part of the survey focuses on linear metric learning approaches, mainly concentrating on the class of Mahalanobis distance learning methods. We then discuss nonlinear metric learning approaches. Finally, we discuss extensions of metric learning, as well as applications to a variety of problems in computer vision, text analysis, program analysis, and multimedia.

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Consider the images in Figure 1.1, and imagine a scenario in which we must compute similarity or distances over pairs of images (for example, for clustering or nearest neighbor classification). A basic question that arises is precisely how to assess the similarity or distance between the pairs of images. For instance, if our goal is to find matching faces based on identity, then we should choose a distance function that emphasizes appropriate features (hair color, ratios of distances between facial keypoints, etc). But we may also have an application where we want to determine the pose of an individual, and therefore require a distance function that captures pose similarity. Clearly other features are more applicable in this scenario. To handle multiple similarity or distance metrics, we could attempt to determine by hand an appropriate distance function for each task, by an appropriate choice of features and the combination of those features. However, this approach may require significant effort and may not be robust to changes in the data. A desirable alternative — and the focus of this survey — is to apply *metric learning*, which aims to automate this process and learn task-specific distance functions in a supervised manner.

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Fig. 1.1 Example face data set. In one application, our notion of "distance" between faces may depend on the pose, whereas in another application it may depend on the identity.

A possible informal formulation of the metric learning problem could be given as follows: given an input distance function $d(\boldsymbol{x}, \boldsymbol{y})$ between objects \boldsymbol{x} and \boldsymbol{y} (for example, the Euclidean distance), along with supervised information regarding an ideal distance, construct a new distance function $\tilde{d}(\boldsymbol{x}, \boldsymbol{y})$ which is "better" than the original distance function (we could also easily replace "distance" with "similarity," and d with s for some similarity function $s(\boldsymbol{x}, \boldsymbol{y})$). This survey will focus, for the most part, on learning distance functions $\tilde{d}(\boldsymbol{x}, \boldsymbol{y})$ of the form $d(f(\boldsymbol{x}), f(\boldsymbol{y}))$ for some function f — that is, we learn some mapping f and utilize the original distance function over the mapped data. We will denote this approach as global metric learning methods, since they learn a single mapping f to be applied to all the data.

One possible drawback to the above definition of metric learning is that it assumes that we have at least some supervision available to learn the new distance; the fact that we assume supervision seems somewhat arbitrary. Take, for instance, dimensionality reduction: linear methods such as principal components analysis can be viewed as constructing a linear transformation P to be applied globally to the data, in an unsupervised manner. The resulting distance between objects is therefore d(Px, Py), and one may claim that this is also a form of metric learning. In contrast, the methods we study typically have supervised information regarding the structure of the desired distance function. For example, one popular form of supervision — relative distance constraints — assumes we may not know the target distance between pairs of instances, but does assume we know that object x is more similar to y than it is to z. The fact that the supervised information is a function of the ideal distance (or similarity) is key to distinguishing the methods we study in this survey from other existing techniques. Furthermore, incorporating such supervision lends itself to interesting algorithmic and analysis challenges, as we will see. Thus, in this survey we will mainly focus on metric learning as a supervised learning problem.

We will break down global metric learning into two subclasses linear and nonlinear. For both cases, we will mainly focus on the case where the input distance function is the Euclidean distance, i.e., $d(\boldsymbol{x}, \boldsymbol{y}) = \|\boldsymbol{x} - \boldsymbol{y}\|_2$. In the linear case, we aim to learn a linear mapping based on supervision, which we can encode as a matrix G such that the learned distance is $\|G\boldsymbol{x} - G\boldsymbol{y}\|_2$. This paradigm is by far the most prevalent in the metric learning community due to the fact that many of the resulting formulations are tractable (at the least, local solutions can be found easily). To achieve convexity, many methods assume that G is square and full-rank, leading to convex optimization problems with positive semi-definiteness constraints. We will discuss such methods in Section 2.

We study nonlinear methods for global metric learning in Section 3. In this case, the distance function is the more general $d(\boldsymbol{x}, \boldsymbol{y}) =$ $\|f(\boldsymbol{x}) - f(\boldsymbol{y})\|_2$. One of the most well-understood and effective techniques for learning such nonlinear mappings is to extend linear methods via kernelization. The basic idea is to learn a linear mapping in the feature space of some potentially nonlinear function ϕ ; that is, the distance function may be written $d(\boldsymbol{x}, \boldsymbol{y}) = \|G\phi(\boldsymbol{x}) - G\phi(\boldsymbol{y})\|_2$, where ϕ may be a nonlinear function. While it may not appear that we have gained anything by this, if we further assume that we can compute

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the kernel function $\kappa(\boldsymbol{x}, \boldsymbol{y}) = \phi(\boldsymbol{x})^T \phi(\boldsymbol{y})$, then it turns out that we may efficiently learn G in the input space using extensions of linear techniques. Crucially, the resulting algorithms scale independently of the dimensionality of the feature space of ϕ , allowing us to utilize kernel functions whose embedding functions may be extremely highdimensional (or even infinite-dimensional, as in the Gaussian kernel). A core result that we discuss is a representer theorem that demonstrates when such metrics may be learned. Beyond kernelization, we discuss some other proposed methods for nonlinear metric learning, including methods based on neural networks.

The goal of the survey is to provide an overview of recent advances in metric learning. For the sake of clarity, we will attempt to present as much of the literature as possible under a unified framework. Of course, given the broad scope of the metric learning problem, and the fact that not all material fits neatly into such a unified presentation, we will have to divert from the main presentation from time to time. In addition to presenting the main metric learning models and algorithms that have been studied, we also focus on several recent applications, including applications from computer vision, multimedia, and text analysis. It is our hope that this survey will synthesize much of the recent work on metric learning, and inspire new algorithms and applications.

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